

Electric Vehicle Motor (PM BLDC motor)

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Applied to all kinds of Electric Vehicle



Electric bus



Electric car



Electric car



Electric boat

Permanent Magnet Blushless DC Motors



Permanent Magnet Blushless DC Motors Datasheet							
Item (Motor+Controller)	Battery voltage (VDC)	Max Torque (N•m)	Rated Torque (N•m)	Max Power (KW)	Rated Power (KW)	Max Speed (rpm)	
PM15A+PMC15A	144	100	48	25	15	6000	
PM20A+PMC20A	144	150	76	30	20	6000	
PM20B+PMC20B	288	150	70	40	20	6000	
PM30A+PMC30A	288	200	82	50	30	7000	
PM30B+PMC30B	320	200	82	50	30	9000	
PM30C+PMC30C	288	250	106	60	30	4000	
PM40A+PMC40A	288	250	106	80	40	5000	
PM40B+PMC40B	280	330	140	80	40	4000	
PM50A+PMC50A	352	420	220	90	50	5000	
PM75A+PMC75A	384	700	330	150	75	5000	

20KW System User's Manual

1 System Introduction

This system consists of motor and controller introduced as follows.

1.1 Motor

In this system PM motor is cooled by water and made of the following parts.

1.1.1 Stator

Stator comprises of casing and winding core.

1.1.2 Rotor

Rotor consists of rotor shaft and permanent magnet block core.

1.1.3 covers

Front cover is of a spigot for installation and rear cover has tapped holes for installation of speed sensor. There are high-quality deep-groove sealed and self oiling bearings in the front cover and the rear cover.

1.1.4 Speed sensor and protective cover

Speed sensor located on the rear end of the motor is kept from damage by protective cover. Its stator is fixed on the rear end-cover and its rotor is fixed on the motor shaft.

1.1.5 Three-phase lead-out cables

Three-phase lead-out cables is connected with the motor stator windings respectively and kept in connection with the cables of the controller by the same color mark at the terminal of each cable during working.

1.1.6 Motor serial number

Only one serial number is allocated to each motor and stamped on the fin of the motor casing, shown in the follow picture.



1 System Introduction

1.2 Controller

In the system controller cooled by water comprises the following parts.

1.2.1 Radiator

Radiator consists of aluminum heatsink and water channel parts.

1.2.2 Housing

The housing made of bended steel sheet keeps the electrical components from damage and its surface is painted with powder.

1.2.3 Main circuit

Main circuit consists of power device, electrolysis capacitors and absorption capacitors.

1.2.4 Lead-out signal wires

The lead-out signal wires of the controller are used for communication with outer device.

1.2.5 Controller serial number

Only one serial number is allocated to each controller and stamped on the edge of the heatsink, shown in the follow picture.



2、Wiring

2.1 For 96V or above (for reference only)



3、 Circuit Diagram





4. Mounting

4.1 About motor

You can mount motor on the chassis of vehicle through 4 threaded holes in front cover and 4 threaded holes in rear cover with long bolts. And there is an external spigot on the front cover for fixing the motor to connecting plate or gear box. The torque is transmitted by joining the shaft of motor with the shaft of gear box.

You should keep enough space and a well-ventilated area for the natural air-cooled motor from damage.

4.2 About controller

- Keep the area around controller clean and dry. Avoid direct exposure to high temperature, wet environment, sunlight and corrosive air.
- Fix the controller on a level frame through four holes in the heatsink and add cushion for a vibratory place.
- Keep an ambient temperature of below 45° C.

5. Communication Protocol

We use serial communications interface (SCI) in the controller for communication and send the state information of controller timely. You can also select CAN (controller area network) for communication as need.

6. Protective Functions

We have some protective functions for the controller, described as follows.

function	description				
	Once the power modules detect overcurrent or overheat, the				
	controller will close off any output and give an alarm, and				
Power modules	switch off the main contactor. You can recover the system				
fault	running by turning key switch to "on" position to reset the				
	system. If this arises repetitively, it is regarded as a fault.				
	Once the circuit detects the output current is greater than the set				
	value, the controller will close off any output and give an				
Overcurrent	alarm, and switch off the main contactor. You can recover the				
	system running by turning key switch to "on" position to reset				
	the system. If this arises repetitively, it is regarded as a fault.				
	When the voltage of DC bus is over max. allowed value during				
	brake or in any term, the controller will close off any output and				
Overvoltage	give an alarm.				
Overvoltage	You can recover the system running by turning key switch to				
	"on" position to reset the system. If this arises repetitively, it is				
	regarded as a fault.				
	Electronic thermal sensitive relay for motor overload makes an				
	inverse proportion between time and load. It will keep an				
Electronic thermal	accumulation of repeated heat, and will ignore the heat arising				
sensitive relay	contingently. It will give an alarm for motor overload instead of				
	closing off the controller output.				
T I.o. do	When the voltage of battery is under the low voltage threshold				
Undervoltage	(this value is adjustable as you need), the controller will close				
	off any output and give an alarm.				

	When the temperature of the heatsink is over 45°C, the fans			
	begin to work. When it is below 40°C, the fans will be switched			
	off. And when it is over 75°C, the controller will give an alarm			
overheat	and decrease the output torque by a half, when it is still up to			
	85°C, the controller will close off any output and give an alarm.			
	The system will work again when the temperature drop to 70°C			
	after the half torque reduced.			
	When motor speed is up to the top value, the controller will			
Top motor speed	reduce the torque output. When the speed is still up to 6500rpm,			
	the controller will close off any output.			
	An output of throttle potentiometer arises while power on the			
Throttle pedal	system, the controller will close off any output.			

7. Maintenance

7.1 About motor

- Clean dust and smear on the surface of motor periodically.
- Please trained technician to replace jacket of the lead-out cables of motor if necessary.

7.2 About controller

- Don't wash the controller in spite of the water-proof design.
- Don't open the cover of controller unless necessary indeed.
- Clean dust and smear on the surface of controller periodically.
- Don't test the control circuit with high-resistance meter.
- Begin to maintain, repair and reconnect the cables after one minute power off, and protect you from electrical shock or damage components of the controller.



8. Troubles and Solutions

8.1 About motor

8.1.1 Insulating resistance to ground

Insulating resistance to ground of motor in our factory is great than or equal to $20M \Omega$. It will be less than $2 M \Omega$ when the motor is wetted, you should dry the motor before using it again.

8.1.2 hard to startup

Check mechanical and electrical parameters of the motor step by step, it is only permitted to break down and install motor by trained technician if necessary.

• The motor can not run at absence of phase.

8.2 About controller

Here are some troubles, possible causes and solutions, described as follows.

trouble	possible causes	solutions		
over-current	power device breakdown	Exchanged power device by		
or power device	Grounded or shorted at load	trained technician. Check the		
defect	side.	cables motor and output cables.		
unstable running	abnormal voltage output due	Exchanged power device by		
with much noise	to power device breakdown	trained technician.		
no response to	Fuse tube onboard breakdown	Replace fuse tube (beside the		
power on	or without precharge.	16-pin connector). If need,		
		check and replace the resistor		
		and relay for precharge.		
unable to rotate	improper cables connection	Check and correct cables		
but wobbling		connection		
and without				
protective signal				
output				

Appendix A: Product Specification

Parameter	Unit	Value	Parameter	Unit	Value
Rated power	kW	20	Peak tore	ue <i>N.m</i>	150
Battery voltage	V	144	Sizes	mm	Ф238×245
Nominal speed	rpm	3200	Speed range	rpm	0-6000
Efficiency	%	95	Winding		Y-type
			connection		
Insulation		class F	Protection		IP55
Cooling		coolant	Weight	kg	46

A1: Motor parameters (PM20A)

A2: Controller parameters (PMC20A)

parameter	unit	value	parameter	unit	value
Max. capacity	kVA	45	5 Input voltage		144
Output voltage	V	84	Current rating	Α	135
Ambient temperature	°C	-25-60	Peak current	A	250
efficiency	%	95	Protection		IP54
Cooling		coolant	weight	kg	11.5

Appendix A: Product Specification

A3: System parameters

parameter	unit	value	description
Input voltage	DCV	144	Allowed value is 100~200 Vdc, but
			lower voltage will bring about poor
			ability.
Rated torque	N.m	76	Running in long-time
Max. torque	N.m	150	running time is about 1 minute
Nominal speed	rpm	3200	
Top speed	rpm	6000	Adjustable by user
Speed range	rpm	0-6000	
Torque controlled by			Throttle pedal
Control strategy			Space vector
Communication			SPI
interface			(CAN optional)
Energy regen			Adjusted as need
Protection function			Overvoltage, overcurrent, power
			device default, undervoltage, overload
			and overheat etc.
Speed sensor			Position sensor, power supply 5VDC



Appendix B: Motor Outline and Dim^{ensions}



Appendix C: Controller Outline and









Battery Charger

Vehicle mounted Battery charger



MOSFET or IGBT power unit Capacity: 1~8kW Voltage range: 36~420V Current: 3~150A Suitable for LiFePO4 or Lead acid battery Application: EV car

Fast charge Battery Charger



IGBT power unit Capacity:8~50kW Voltage range: 288~600V Current:10~150A Suitable for LiFePO4 or Lead acid battery Application: EV car ,E-bus

DC-DC Converter

The DC/DC converter supplies the $12V_{\circ}$ 24 V circuitry of the electric vehicle with power from the traction battery. The converter can be used with or without a 12V backup battery .If the backup battery is not charged but the DC/DC has input voltage , the charge control lamp lights up.



Input voltage (V)	50-200	160-300	280-420	0-600		
Output voltage(v)	12、13.8、24	12、13.8、24	12、13.8、24	0-600v		
POWER(w)	300-600	600-1200	1000-3000	300-20000		
Dimensions(DxWxH)	250*180*100mm	270*250*135mm	270*250*135mm			
Weight (KG)	3	6	6			
		Incorrect input con	nnection and breakdown j	protected		
Protecti		Overload and output short-circuit protected				
Flotecu	011	Overheat protected				
	-	Input undervoltage and overvoltage protected				
Output voltage ripple (0-50MHz)		<25mV RMS				
Line/load regulation:		<1%				
EMC-conducted	emissions:	EN 55022 level A				
Safety	:	EN60950				
Input to case i	solation:	1.5kV AC				
Output to case	isolation:	500V DC				
Efficiency (cont.current ,typ.):		86%				
No load current consumption:		max.25mA				
Ambient tempera	ture range:	-25℃ +3 5℃				
Max.ambient ter	mperature:	60°℃				



Pedal

The accelerator pedal can control the motor speed by giving control signal to the controller. It also can adjust the rotation direction shift from CW/CCW. Its effect is as the same as the gas accelerator.









Hall voltage: 4.5~12V IP: water-proof Application: EV-car, Goft car



Hall voltage: 4.5~12V IP: water-proof Application: Goft car, Tour car Output resistor:0~5k IP:water proof Application: EV-car,Goft car



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